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;div><div>In LiDAR, laser light is sent from a source (tran) Tj T*□□BT /F1 12 Tf 50

>The reflected light is detected by the system receiver and the
time of flight (TOF) is used to develop a👄 distance map of the objects i
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t is LiDAR and How Does it Work? - Synopsys</div></span&gt
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t;The object-wise feature extractors project LiDAR point clouds into
 2D representations👄 and generate the object proposals using 2D networks
. Then, they regress the region proposals to predict the 3D boundin
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